# Jonathan A Diller

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## **Research Interests**

My research interests broadly lie in multi-robot planning and tasking. More specifically, I focus on developing planning and tasking algorithms that account for how a robot's actions affect the state of its own systems, how the environment influences its behavior, and how the actions of individual robots impact their ability to coordinate within a team. A common theme in my work is the integration of realistic systems models into both centralized and decentralized algorithms, with an emphasis on bridging theory and practice. I also have a broader interest in Operations Research and Machine Learning.

## Education

Doctor of Philosophy in Robotics	Expected Graduation: August 2025	
Colorado School of Mines		
Advisor: Dr. Qi Han		
Thesis: "Robust Robot Teams; Making Planning for Mult	ti-Agent Systems Reflective"	
Master of Science in Computer Science	May 2022	
Colorado School of Mines		
• GPA: 4.0/4.0		
Bachelor of Science in Computer Science	May 2020	
Pennsylvania State University, Harrisburg		
Minor in Mechatronics Technology		
Minor in Mathematics		
Graduated summa cum laude		
• GPA: 3.99/4.0		

## **Research Experience**

<ul> <li>Research Assistant (Advisor: Dr. Qi Han)</li> <li>Pervasive Computing Systems Group, Colorado School of Mines <ul> <li>Studying and implementing multi-robot projects with focus on energy-aware planning.</li> <li>Writing proposals (contributed to two white papers)</li> </ul> </li> </ul>	July 2020 - Present Golden, CO communication and
<ul> <li>Journeyman Fellow (Mentor: Dr. J. Humann and J. Dotterweich)</li> <li>Army Research Laboratory</li> <li>Researched and developed planning algorithms for mixed drophological developed planning algorithm</li></ul>	June 2024 - August 2024 Golden, CO (remote) one-UGV teams.
<ul> <li>Graduate Research Intern (Mentor: Dr. John Rogers)</li> <li>Army Research Laboratory</li> <li>Researched the topics of task allocation and communication</li> </ul>	May 2023 - August 2023 Adelphi, MD mapping for robot teams.
<b>Research Scholar</b> (Advisor: Dr. Peter Idowu) Penn State Drawdown REU Program	June 2019 - July 2019 Middletown, PA

• Designed and evaluated algorithms for controlling microgrids using PLCs.

#### Research Assistant (Advisor: Dr. Javad Khazaei)

Pennsylvania State University

March 2019 - June 2019 Middletown, PA

• Researched and developed microcontroller applications for use in renewable energy projects.

## **Publications**

<sup>†</sup> Student mentees, acceptance rate listed when known

#### **Under Review**

[R1] **J. Diller**, Q. Han, and M. Desaulniers<sup>†</sup>. *"Holistic Framework for Multi-Drone Data Collection in IoT Systems."* Under review at the IEEE Internet of Things Journal.

#### **Journal Papers**

- [J1] **J. Diller**, J. Rogers, Q. Han, and N. T. Dantam. "*Communication Mapping for Robot Teams*." Accepted for publication at the IEEE Transactions on Field Robotics, 2025.
- [J2] **J. Diller**, Q. Han. "*Energy-Aware Drone Path Finding with a Fixed-Trajectory Ground Vehicle*." Published in the ACM Journal on Autonomous Transportation Systems, 2025.

#### **Conference Papers**

- [C1] J. Diller, Y. S. Teoh<sup>†</sup>, R. Byers<sup>†</sup>, Q. Han, J. G. Rogers, and N. T. Dantam. "Failure-Aware Tasking for Teams of Drones." In proceedings of the International Conference on Distributed Computing Systems (ICDCS), 2025. Acceptance rate: 19.7%.
- [C2] J. Diller, Q. Han, R. Byers<sup>†</sup>, J. Dotterweich, and J. Humann. "Hitchhiker's Guide to Patrolling: Path-Finding for Energy-Sharing Drone-UGV Teams." In proceedings of the International Conference on Autonomous Agents and Multiagent Systems (AAMAS), 2025. Acceptance rate: 24.5%.
- [C3] C. Wang, J. Diller, and Q. Han. "LLM for Generating Simulation Inputs to Evaluate Path Planning Algorithms." In proceedings of the International Conference on Machine Learning and Applications (ICMLA), 2024. Acceptance rate: 24.3%.
- [C4] J. Diller, P. Hall<sup>†</sup>, and Q. Han. "Holistic Path Planning for Multi-Drone Data Collection." In proceedings of the International Conference on Distributed Computing in Smart Systems and the Internet of Things (DCOSS-IoT), 2023. Acceptance rate: 38.4% (short paper).
- [C5] J. Diller and Q. Han. "Energy-Aware UAV Path Planning with Adaptive Speed." In proceedings of the International Conference on Autonomous Agents and Multiagent Systems (AAMAS), 2023. Acceptance rate: 23.3%.

- [C6] J. Diller, P. Idowu, J. Khazaei, "Load-Leveling Trainer for Demand Side Management on a 45kW Cyber-Physical Microgrid," Texas Power and Energy Conference 2020 (TPEC), 2020
- [C7] J. Diller, B. Trussell, J. Khazaei, P. Idowu, "Hardware Development of a Three-Phase 3.5 kW SiC Converter with Sinusoidal PWM," Texas Power and Energy Conference 2020 (TPEC), 2020

#### Workshop Papers

- [W1] **J. Diller**, N. Dantam, J. Rogers, and Q. Han. "*Communication Jamming-Aware Robot Path Adaptation*." In proceedings of the International Workshop on Distributed Collective Intelligence (DISCOLI), 2023.
- [W2] P. Hall<sup>†</sup>, J. Diller, A. Moon<sup>†</sup>, and Q. Han. "DroNS-3: Framework for Realistic Drone and Networking Simulators." In proceedings of the Workshop on Micro Aerial Vehicle Networks, Systems, and Applications (DroNet), 2023.
- [W3] J. Diller, P. Hall<sup>†</sup>, C. Schanker<sup>†</sup>, K. Ung<sup>†</sup>, P. Belous<sup>†</sup>, P. Russell<sup>†</sup>, and Q. Han. "ICCSwarm: A framework for Integrated Communication and Control in UAV Swarms." In proceedings of the Workshop on Micro Aerial Vehicle Networks, Systems, and Applications (DroNet), 2022.

#### **Extended Abstracts & Demonstrations**

- [A1] M. Hatch<sup>†</sup>, C. Fellinge<sup>†</sup>, J. Diller, and Q. Han. "ROARQuad: Robust, Open Academic Research Quadcopter." Accepted for demonstration at the International Conference on Mobile Systems, Applications, and Services (Mobisys), 2025.
- [A2] **J. Diller**. "Self-Aware High-Level Planning for Robot Teams." Presented at the Cyber-Physical Systems Rising Stars Workshop, 2024. Acceptance rate: 16.4%.
- [A3] J. Diller. "Planning and Coordination for Unmanned Aerial Vehicles." Presented at the International Conference on Autonomous Agents and Multiagent Systems' Doctoral Consortium, 2023.
- [A4] J. Diller, Q. Han, C. Dreyer, F. Rossi, S. Bandopadhyay, J.P. de la Croix, A. Rahmani, P. Clark. "Integrated Communication and Controls for Swarms of Small Satellites." Presented at the Inter-Planetary Small Satellite Conference, 2021.

## Awards & Recognitions

2024 Cyber-Physical Systems Rising Star	May, 2024
<ul> <li>Best PhD Poster, C-MAPP, Colorado School of Mines</li> </ul>	Jan, 2024
<ul> <li>Best PhD Poster, C-MAPP, Colorado School of Mines</li> </ul>	Jan, 2023
<ul> <li>Best Elevator Pitch, C-MAPP, Colorado School of Mines</li> </ul>	Feb, 2022
<ul> <li>Graduation Student Marshal for School of Sci., Eng. and Tech.</li> </ul>	May, 2020
Computer Science Outstanding Student, Pennsylvania State University	Apr, 2020

## • Evan Pugh Scholar Award - Senior, *Pennsylvania State University*

- Evan Pugh Scholar Award Junior, *Pennsylvania State University* Apr, 2018
- President's Freshman Award, *Pennsylvania State University*
- Dean's List, *Pennsylvania State University*

## **Teaching Experience**

#### College Teaching Certificate Program

Colorado School of Mines, Trefny Center

- Studied teaching pedagogy and learner-centered teaching practices
- Designed a upper-level undergraduate course to introduce students to robot autonomy

#### **Primary Instructor**

Colorado School of Mines

- CSCI 128: Computer Science for STEM (Fall 2024, Spring 2025)
- Typical class size: 50-70 students

## **Teaching Assistant**

Colorado School of Mines

- CSCI 565: Distributed Systems (Fall 2022)
- CSCI 406: Algorithms (Spr 2021)
- CSCI 261: Programming Concepts (Fall 2020)

## Peer Tutor

Pennsylvania State University

- Tutor students in Computer Science, Mathematics, Physics and Engineering classes.
- Earned CRLA Certified Tutor, Level I Certification.

## **Mentoring Experience**

#### Graduate Students

Matthew Desaulniers, *publications*: [R1] Robert Byers, publications: [C1, C2] Yee Shen Teoh, *publications*: [C1] **Priestly Barigala** 

## **Undergraduate Students**

Cody Fellinge<sup>\*</sup>, *publications*: [A1] Matthew Hatch<sup>\*</sup>, *publications*: [A1] Jack Sigler Ava Moon, *publications*: [W2] Corey Schanker, publications: [W3] Peter Hall<sup>\*</sup>, *publications*: [C4, W2, W3] Kristen Ung<sup>\*</sup>, *publications*: [W3] Philip Belous, *publications*: [W3] Zachary Smeton\*

degree (year conferred) PhD in Robotics MS in Computer Science MS in Robotics (2025) MS in Robotics (2024)

BS in Electrical Engineering (2025) BS in Electrical Engineering (2025) BS in Computer Science (2025) BS in Computer Science Combined BS in CS + EE BS in Computer Science (2023) BS in Electrical Engineering (2022) BS in Computer Science (2022) BS in Computer Science (2021)

August 2017 – May 2020

Golden, CO

Middletown, PA

## Apr, 2019

Apr, 2017

Spring 2016 - Spring 2020

August 2024 – May 2025

Golden, CO

Golden. CO

August 2024 – May 2025

**August 2020 – December 2022** 

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Spring 2023

- International Conference on Unmanned Aircraft Systems

## **Committees**

	•	Graduate Research and Discovery Symposium, Program Chair	2025
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- Graduate Research and Discovery Symposium, Poster Chair 2024
- Mines Research Integrity and Security Committee, Grad. Rep. Fall 2023 - Spring 2024
- Mines Research Council, Graduate Representative
- CS@Mines Research Committee, Student Advocate Spring 2022 - Spring 2023

## **Other Service**

- Graduate Student Government, CS Representative Fall 2022 - Spring 2024
- Graduate Student Seminar Organizer:
  - 6 seminars in 2023
  - 4 seminars and 1 workshop in 2024
  - 2 seminars in 2025

May 2018 – July 2020 Lancaster. PA

## November 2010 - November 2015

San Diego, CA & Okinawa, Japan

## \* Graduated with Undergraduate Research Scholar Distinction

## **Work Experience**

### Robert Bosch GmbH

Embedded Software Developer & Test Intern

- Develop firmware for embedded real-time environments.
- New product prototyping.
- Design and implement automated tests for moving cameras.
- Write documentation for internal procedures.

## United States Marine Corps

KC-130J Crewmaster, Plane Captain

- Last held rank/pay grade: Sergeant/E-5
- Supervised small teams in pre and post flight inspections on C-130J aircraft.

## Service

## **Technical Reviewer**

- IEEE Robotics and Automation Letters
- Pervasive and Mobile Computing Journal
- ACM Journal on Autonomous Transportation Systems
- IEEE International Conference on Pervasive Computing and Communications
- IEEE International Conference on Robotics and Automation.
- IEEE/RSJ International Conference on Intelligent Robots and Systems
- ACM/IEEE International Conference on Cyber-Physical Systems